

Introduction to Artificial Intelligence

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LAAS-CNRS - Équipe TRUST

Summer school: Cyber in Font-Romeu
July 7th 2025

Who am I ?

Philippe Leleux

- Associate professor at INSA de Toulouse, LAAS-CNRS, Equipe TRUST
- Teaching : machine learning for critical embedded systems
- Research :
 - How to make machine learning techniques more "trustworthy" ?
=> *Application to medical diagnostic, pronostic, treatment decision*
 - How to use machine learning for safety (including cybersecurity) ?
=> *Detection of hardware trojans based on micro-architectural signals*



AI

What ? Why ? Where ? When ?

Let's start with some questions

- When did the term artificial intelligence appear ?

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=> 1956, Dartmouth College
- Who among you uses generative AI regularly ?



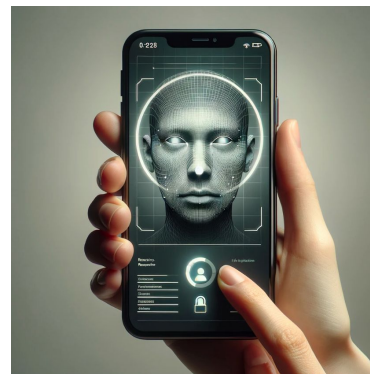
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=> all
- Who has set up machine learning algorithms ?



How many fingers ?

Let's start with some questions

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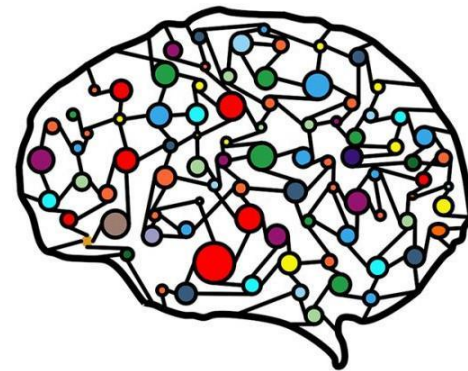
➤ Who has set up machine learning algorithms ?

=> scikit-learn, Tensorflow, Pytorch

=> Typically neural networks



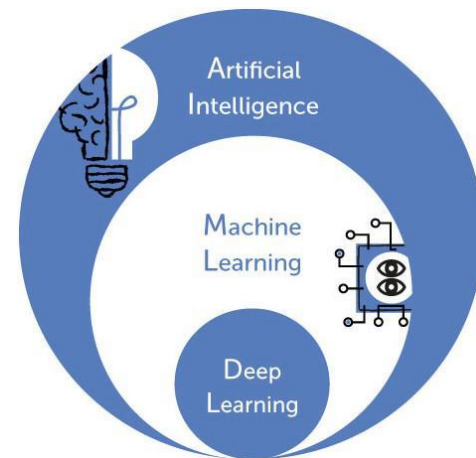
How many fingers ?



What is AI ?

➤ What AI is:

- IA = program trying to imitate human logic (~50s)
- example : 4 legs + 1 sit + 1 back = chair

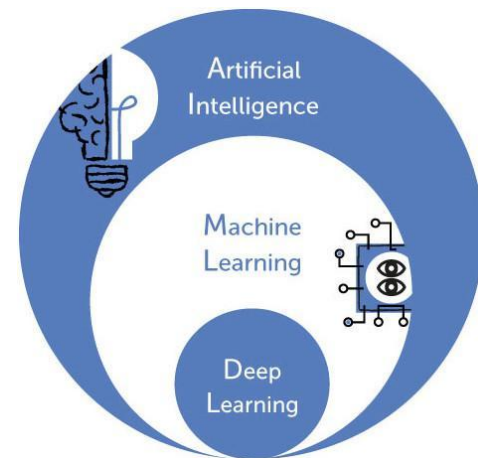


What is AI ?



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 - data => model => answer
 - example : lots of chairs vs. lots of non-chair

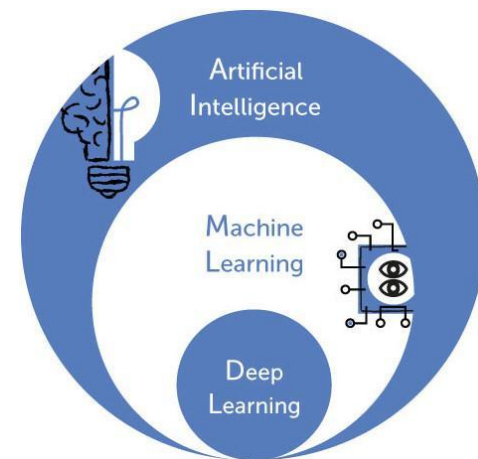
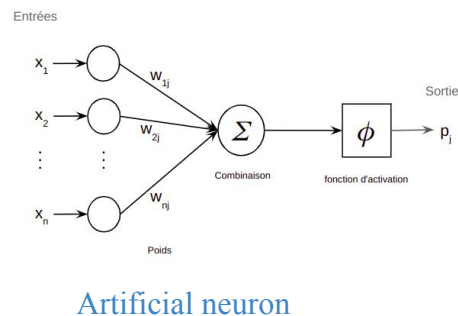
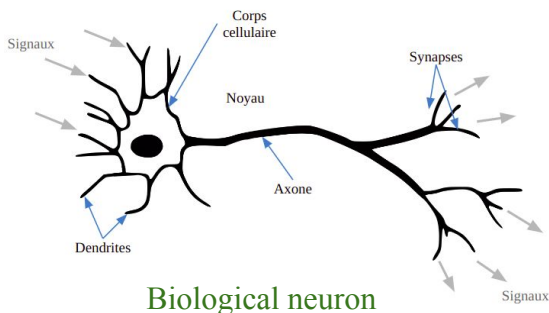


What is AI ?



➤ What AI is:

- IA = program trying to imitate human logic (~50s)
- Machine learning
 - data => model => answer
 - workflow + set of algorithms
- Deep learning : neural networks
 - Inspired from the brain
 - example : facial recognition, ChatGPT, ...



What is AI ?



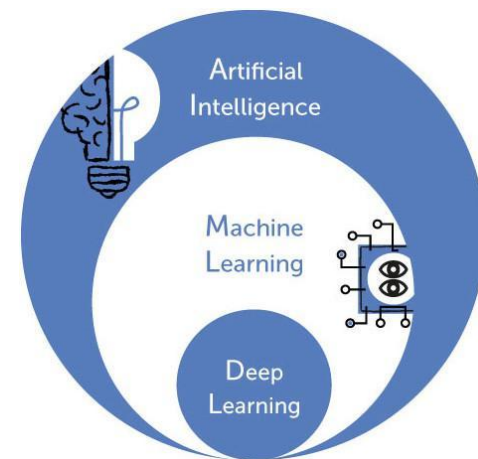
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➤ What AI is **not** :

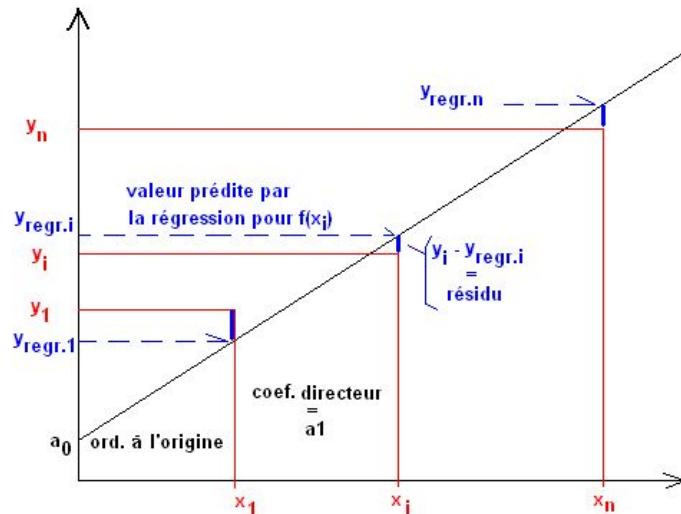
- "Intelligent", "sentient", a "mystical entity"
- A miracle solution to all problems
- A danger for humanity

➤ Must you be an expert to use machine learning ? Certainly not.



What is AI ?

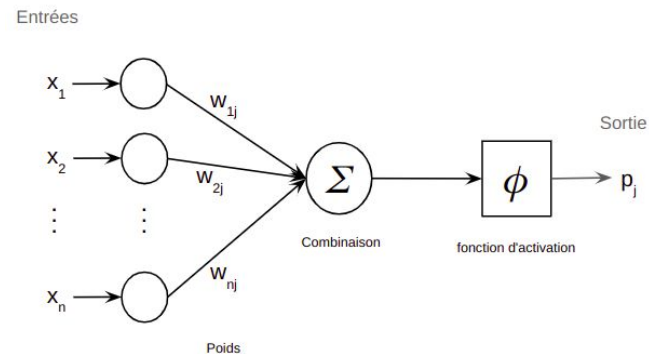
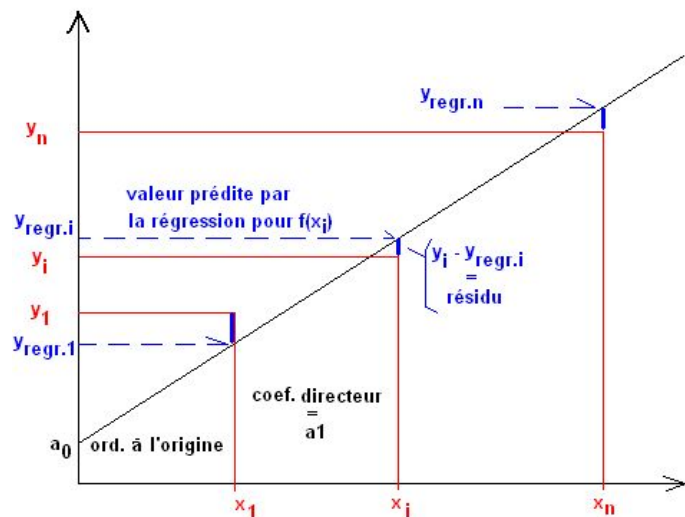
- Must you be an expert to use machine learning ? Certainly not.
- Do you know affine functions ?



What is AI ?

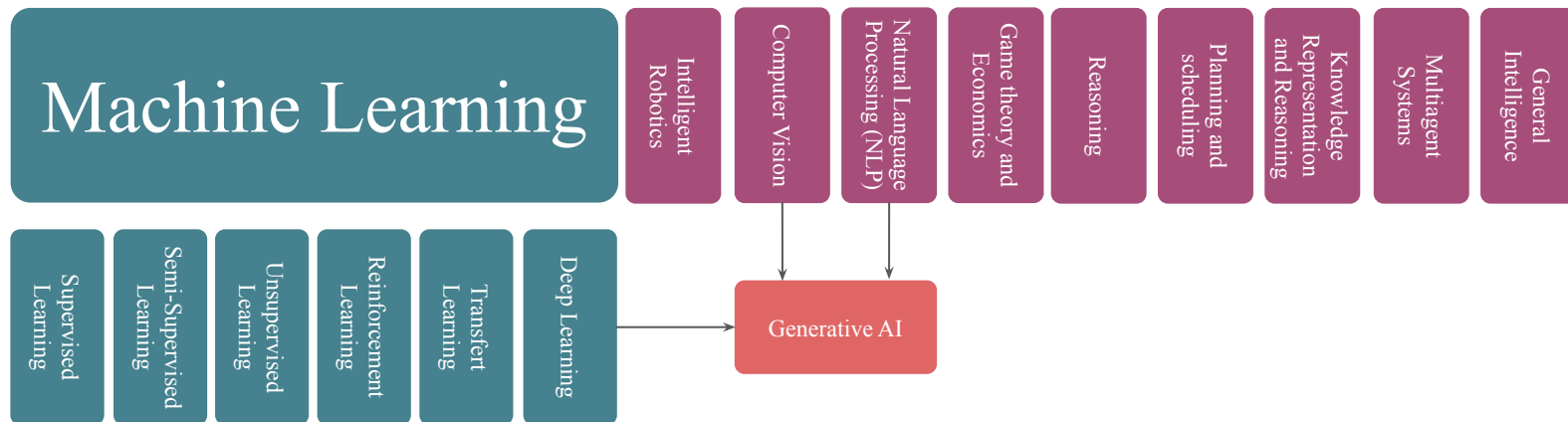
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- Do you know affine functions ?

=> **Congrats, you now know how an artificial neuron works! (mostly)**



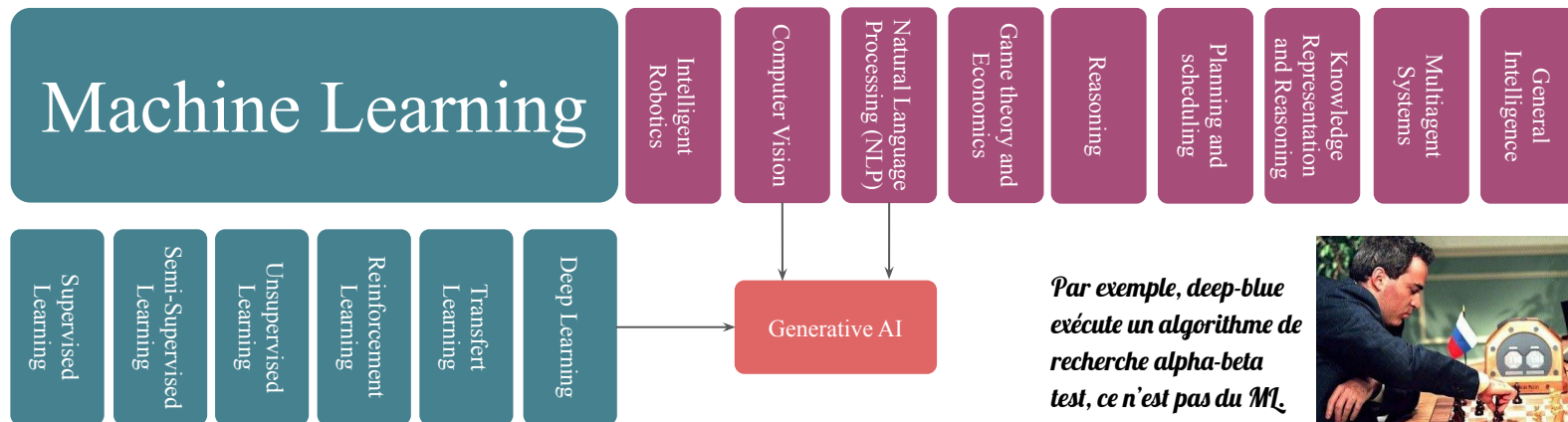
Artificial neuron

Intelligence Artificielle



Machine Learning is a subset of Artificial Intelligence. The term Artificial Intelligence is often misused (buzzword in the sense of global intelligence).

Intelligence Artificielle

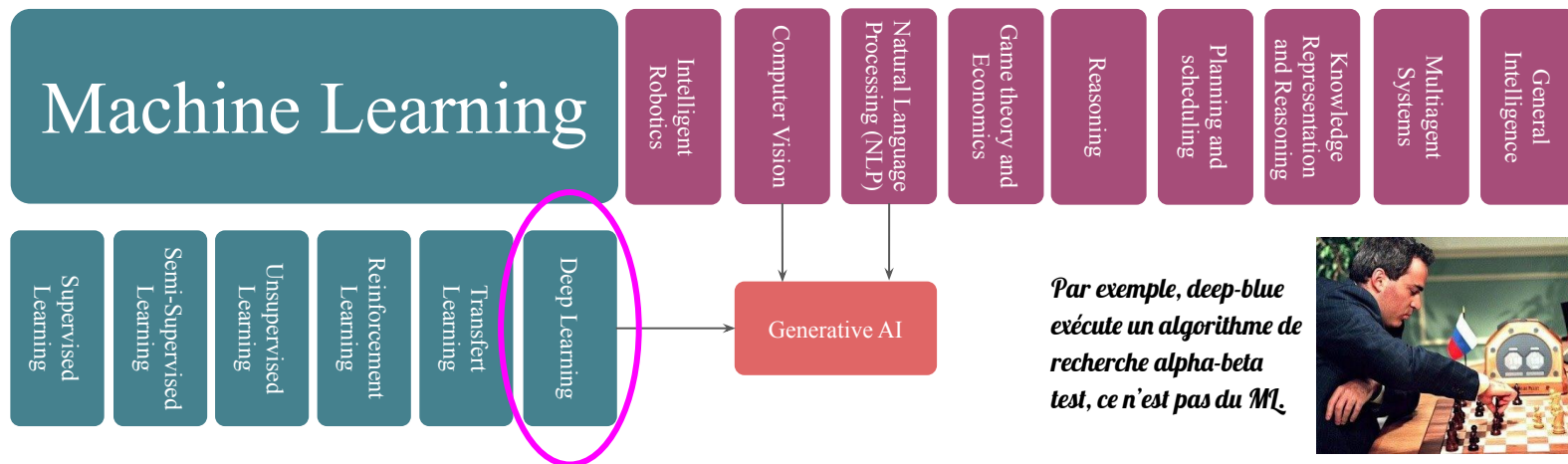


Par exemple, deep-blue exécute un algorithme de recherche alpha-beta test, ce n'est pas du M_L .



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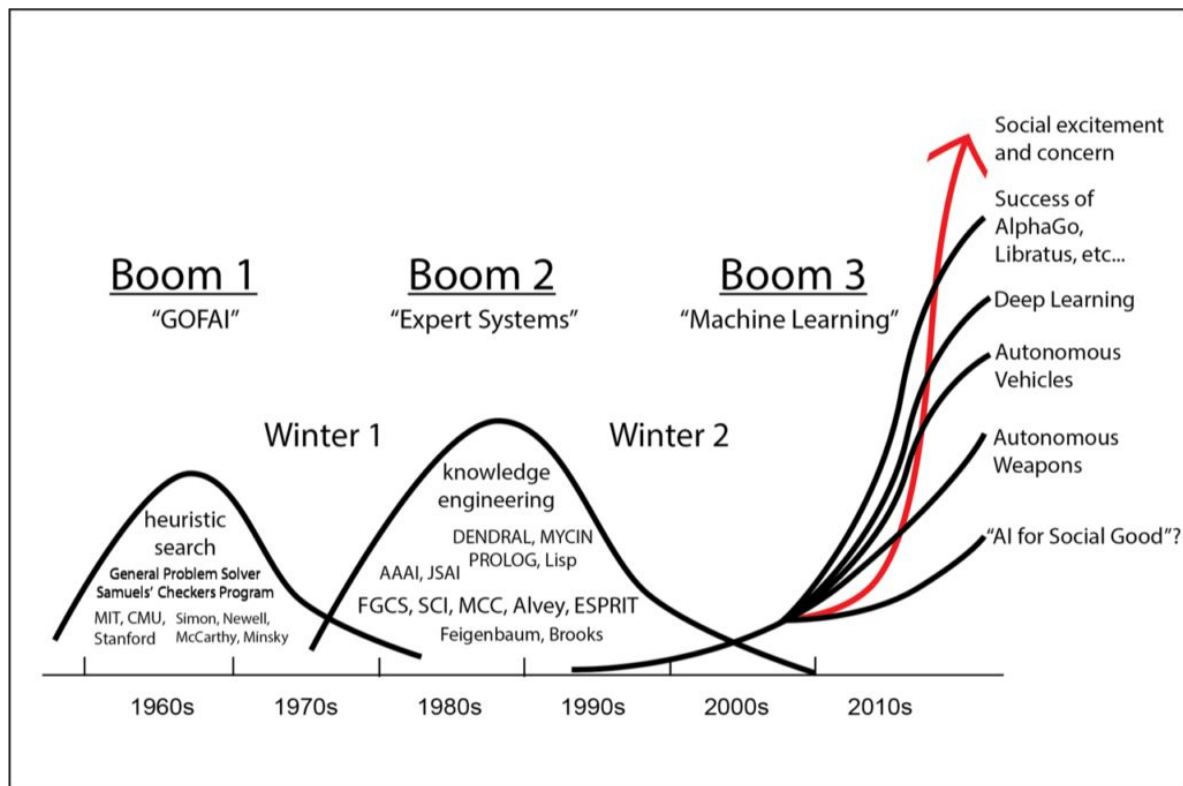


Par exemple, deep-blue exécute un algorithme de recherche alpha-beta test, ce n'est pas du ML.



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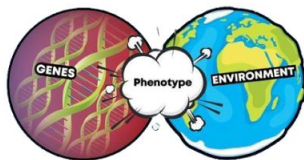
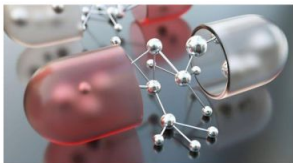
Types of AI and Tasks



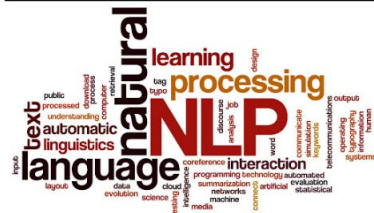
Real-life examples

Welcome to the AI era

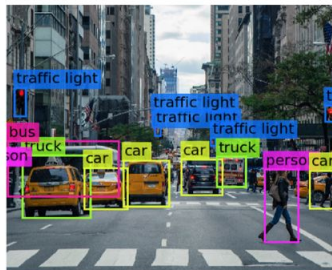
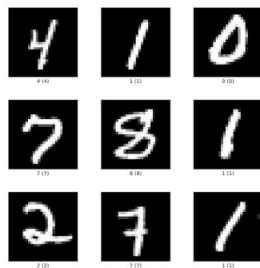
Biology



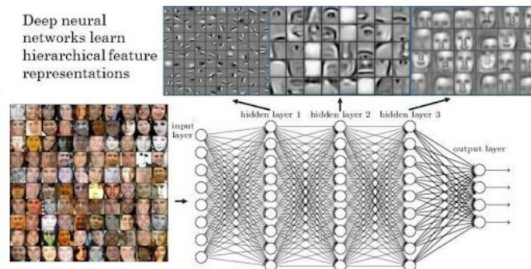
Natural Language Processing



Computer Vision



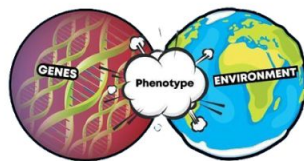
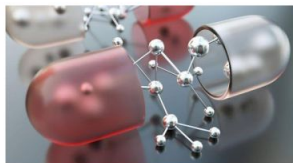
Deep neural networks learn hierarchical feature representations



Real-life examples

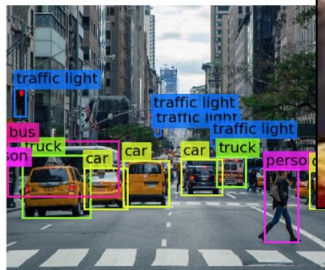
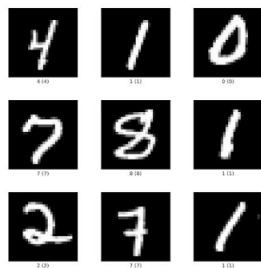
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Natural Language Processing

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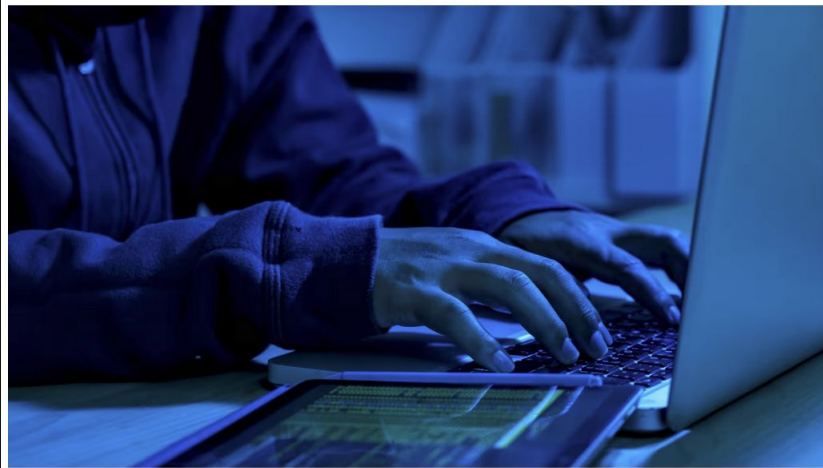


Finance worker pays out \$25 million after video call with deepfake 'chief financial officer'



By Heather Chen and Kathleen Magramo, CNN

2 minute read · Published 2:31 AM EST, Sun February 4, 2024



Real-life examples Welcome to the AI era

Natural Language Processing



Real-life examples

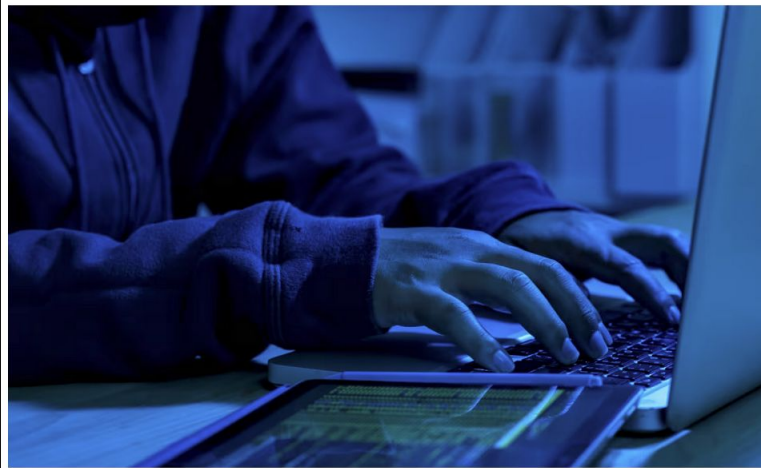
Welcome to the AI era

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2

7

1



Natural Language Processing

Viral scam: French woman duped by AI Brad Pitt love scheme faces cyberbullying

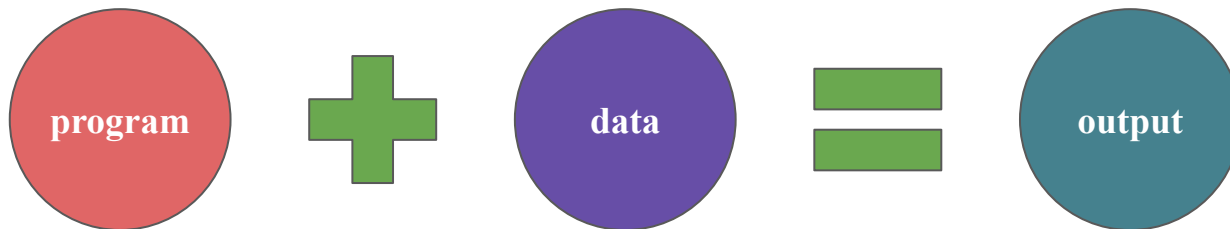


AI How ?

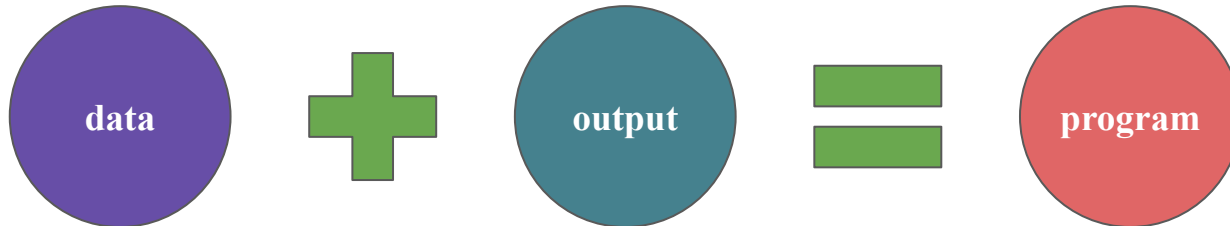
AI
Machine Learning
How ?

Machine learning Paradigm

➤ Traditional approach

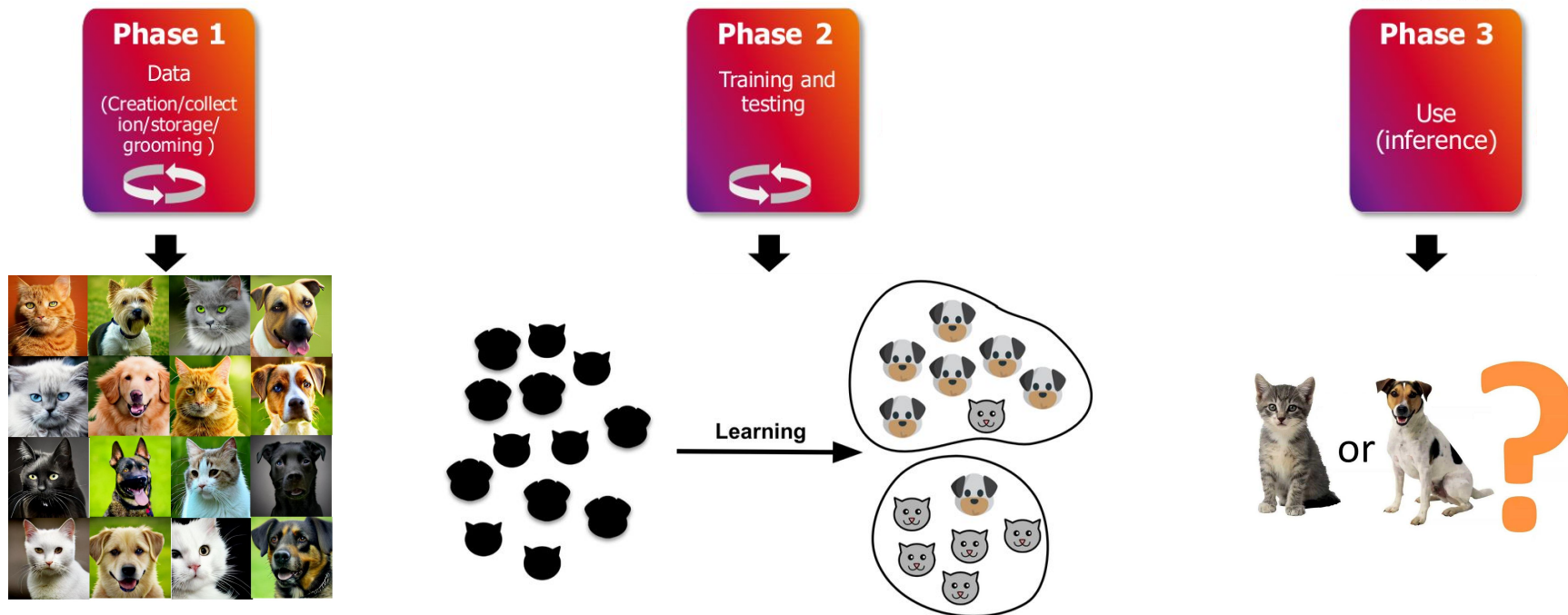


➤ Machine Learning



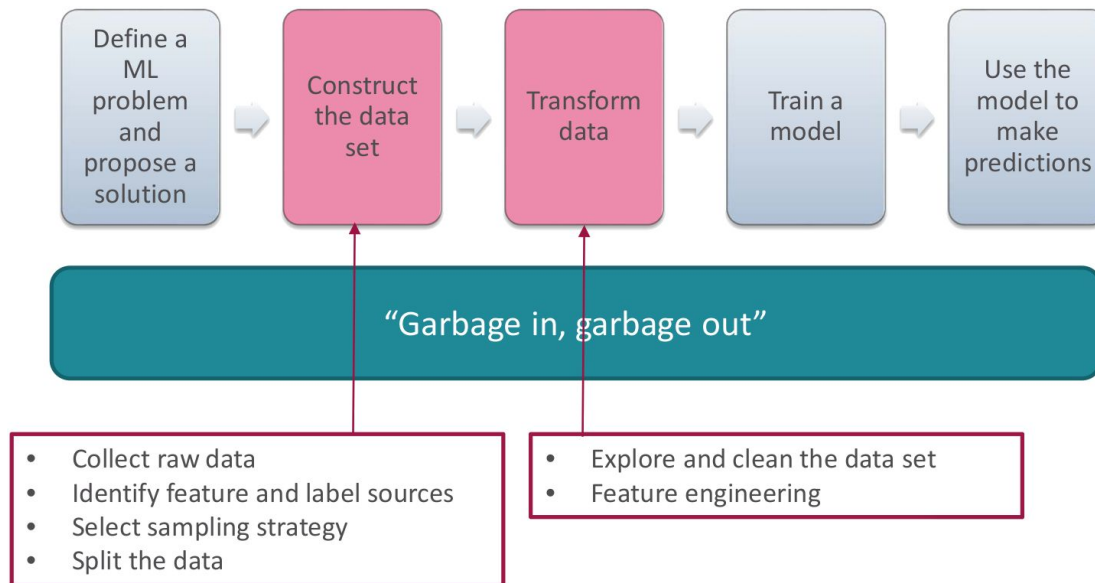
“Machine Learning is the field of study that gives computers the ability to learn without being explicitly programmed”. Arthur Samuel (1959)

Machine learning Steps



Machine learning

Data preparation



What types of data ?

How much of the whole development process is spent on data ?

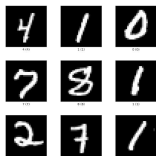


Dataset MNIST :

<https://www.kaggle.com/datasets/hojjatk/mnist-dataset>

Machine learning


3 types of learning



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1. **Supervised learning** : from labelled inputs, train a model

=> e.g. classification : what number is  ?

The patient has cancer ?

Machine learning

3 types of learning

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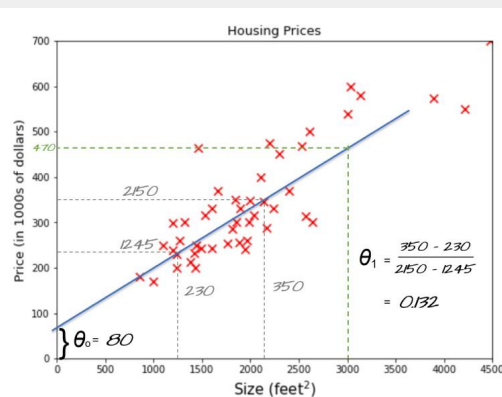
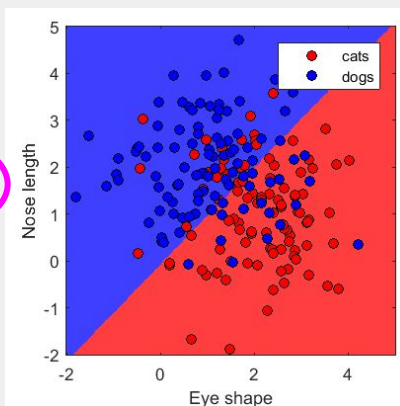
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1. **Supervised learning** : from labelled inputs, train a model

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classification
(qualitative)



regression
(quantitative)

Machine learning


3 types of learning



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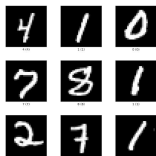
2. **Unsupervised learning** : from unlabelled inputs, find a structure

=> e.g. clustering : group together   ;

Group of patients => specific drug

Machine learning

3 types of learning



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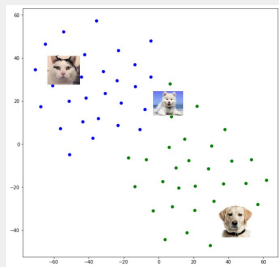
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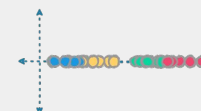
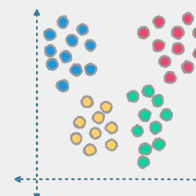
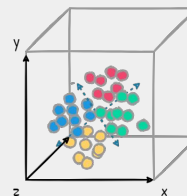
=> e.g. clustering : group together **1** **1** ;

Group of patients => specific drug

clustering



dimension reduction



Machine learning

3 types of learning



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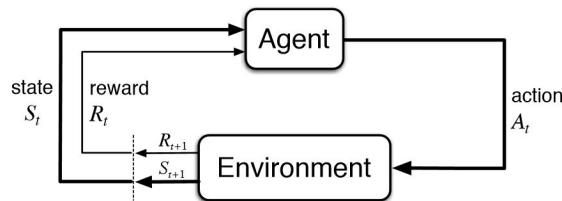
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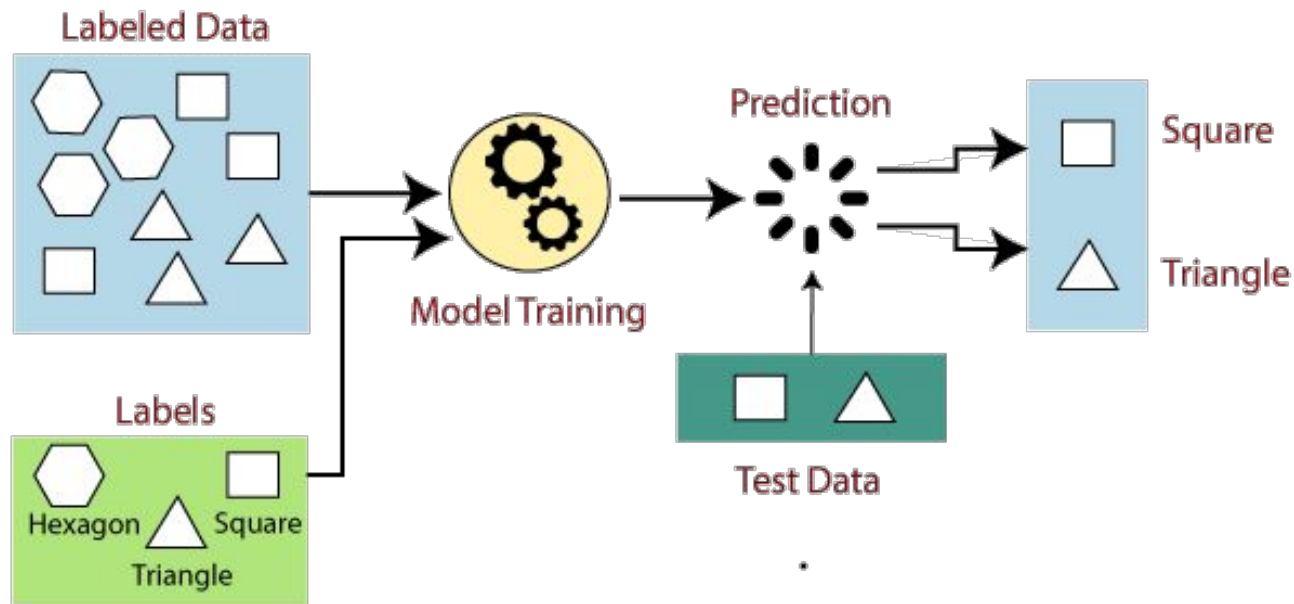
3. **Reinforcement learning** : from environment and reward, train an agent



Supervised learning

Supervised learning Task

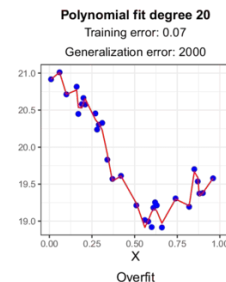
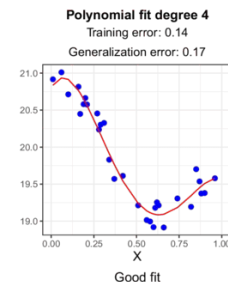
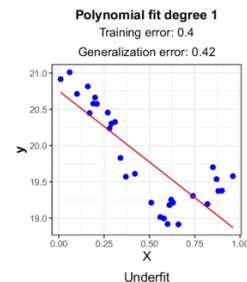
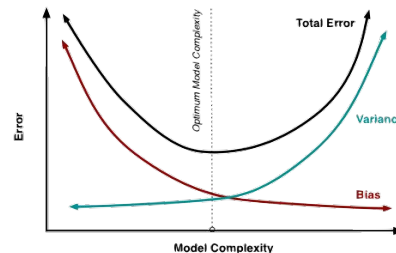
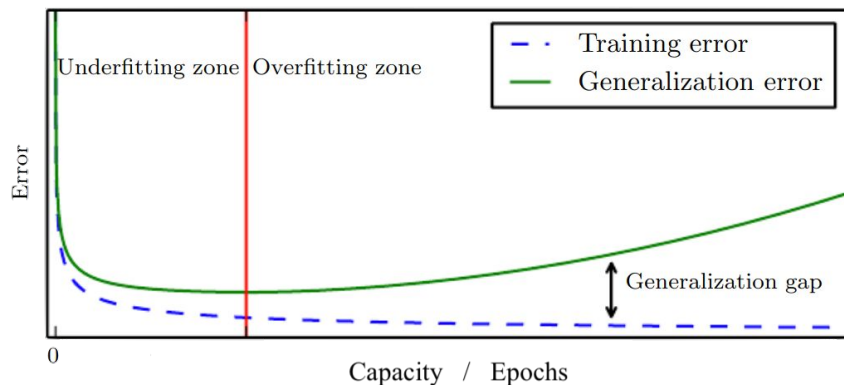
- Input : dataset with labels (given by experts)



Supervised learning Task

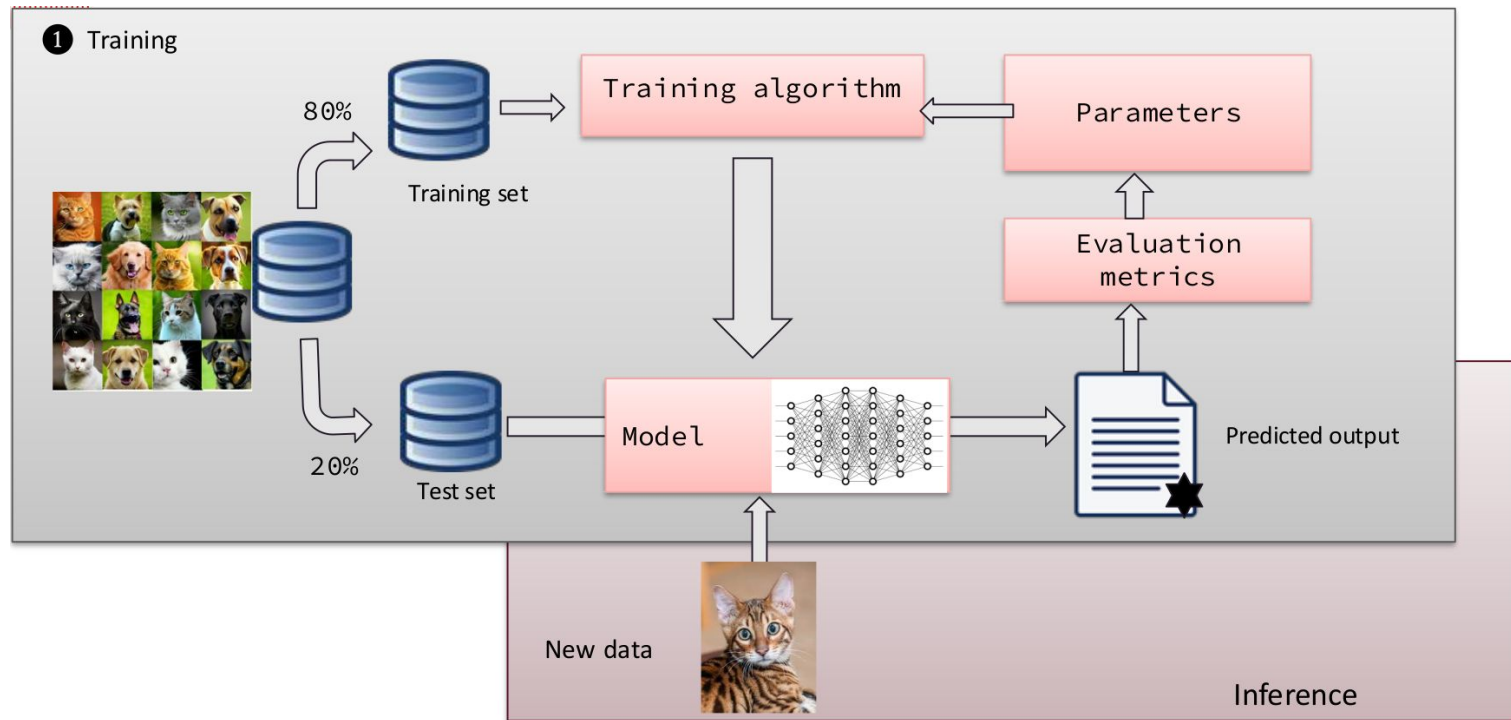
- **Goal** : find f such that $\hat{y}_i = f(x) \approx y_i$ by minimizing an error/loss function
- For example: Mean Squared Error (MSE) :

$$\frac{1}{m} \sum_{i=1}^m (\hat{y}_i - y_i)^2$$



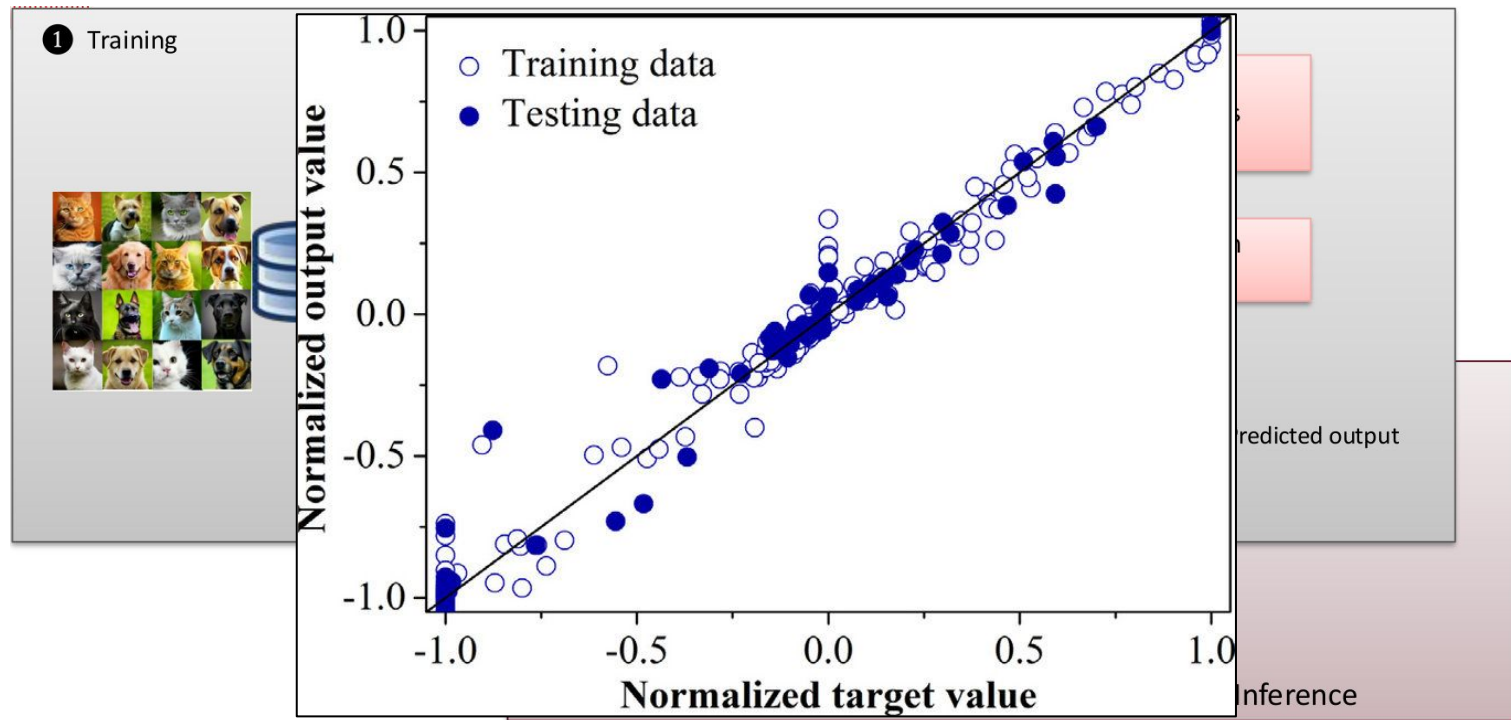
Supervised learning

Classical workflow



Supervised learning

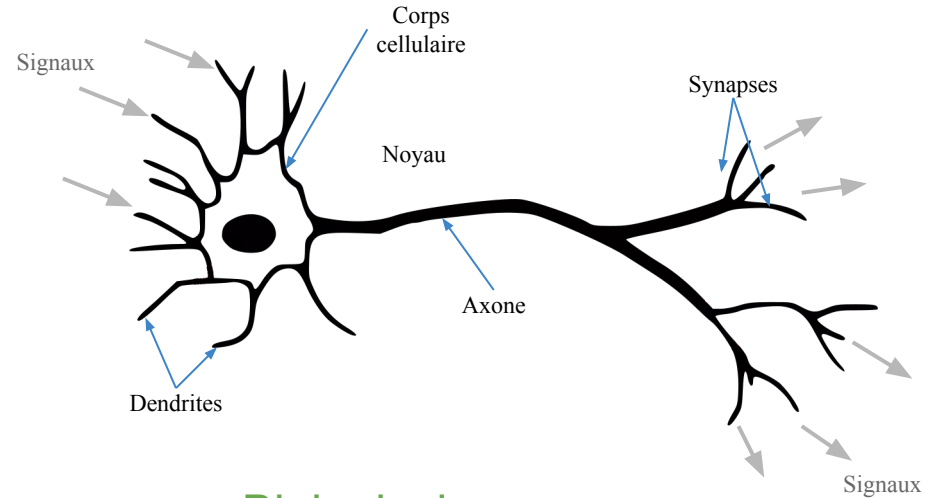
Classical workflow



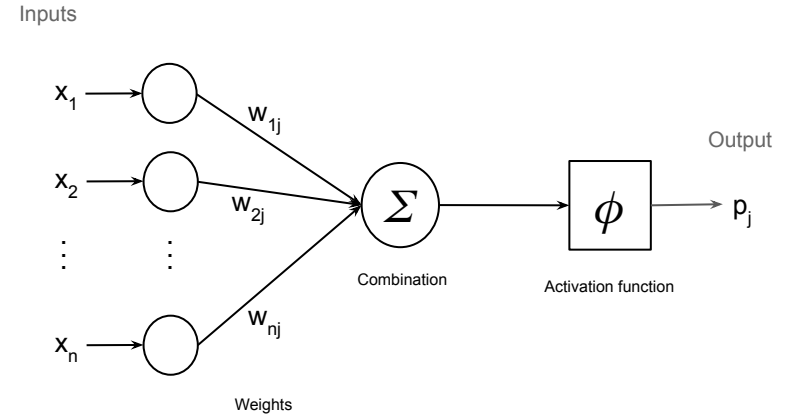
Deep learning

Neural networks

biomimicry



Biological neuron



Artificial neuron

First neural network

Fruits classification

Labels



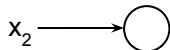
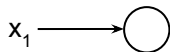
Data

x_1	x_2
2.5	5.5
2.7	5.6
2.9	5.3
3.1	5.2
3.3	5.7

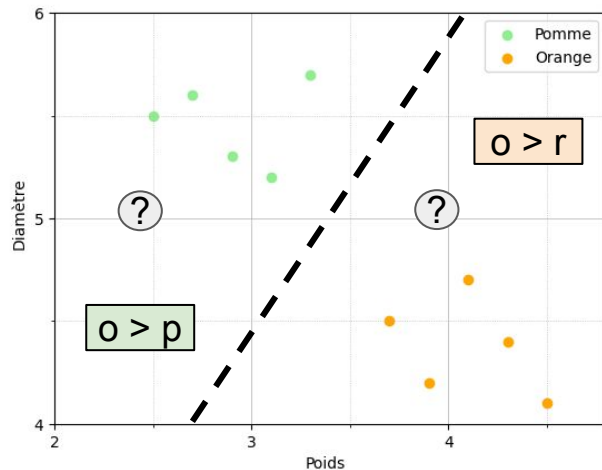
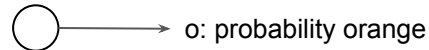
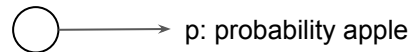
x_1	x_2
3.7	4.5
3.9	4.2
4.1	4.7
4.3	4.4
4.5	4.1

x_1 = weight
 x_2 = diameter

layers: input



output



First neural network

Combining inputs

Labels

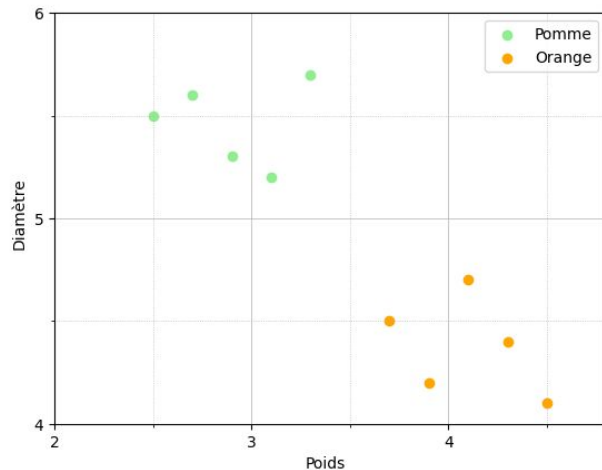


Data

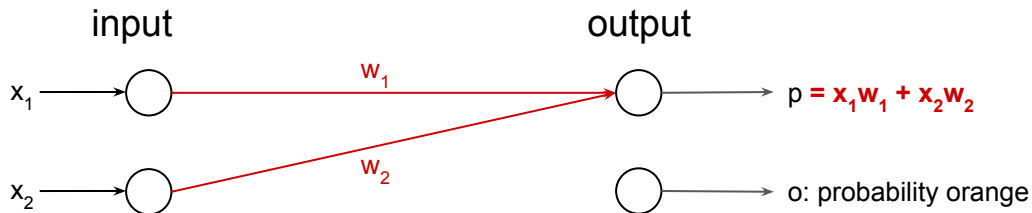
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layers:



First neural network

Linear separation

Labels

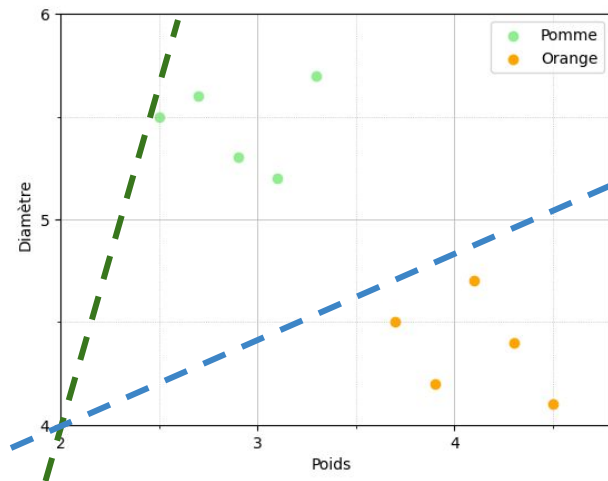


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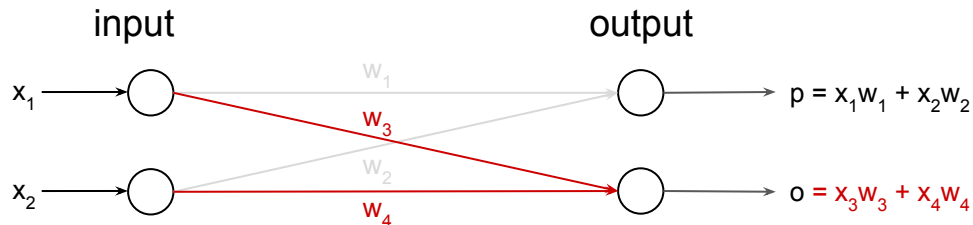
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 x_2 = diameter



layers:



First neural network

Affine separation: bias

Labels

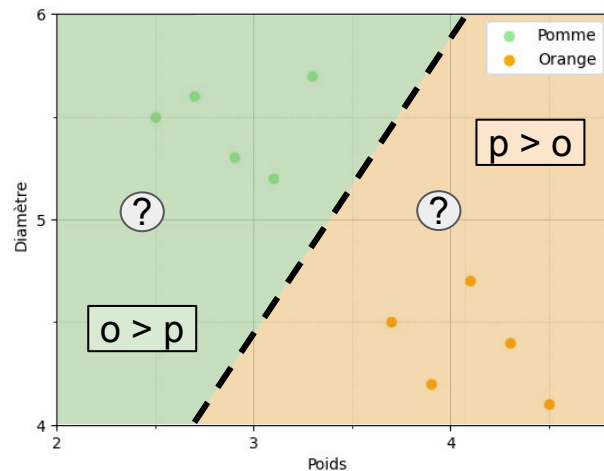


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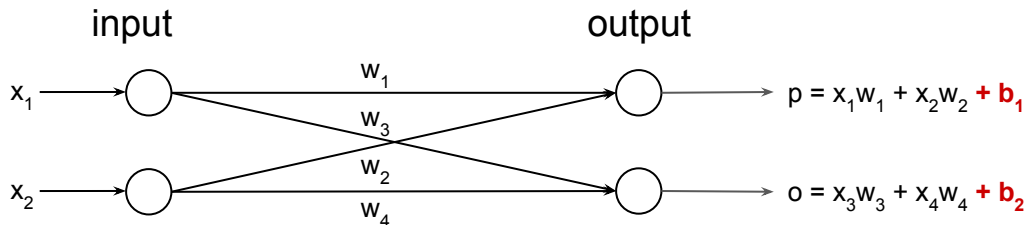
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layers:



First neural network

Non-linear separations?

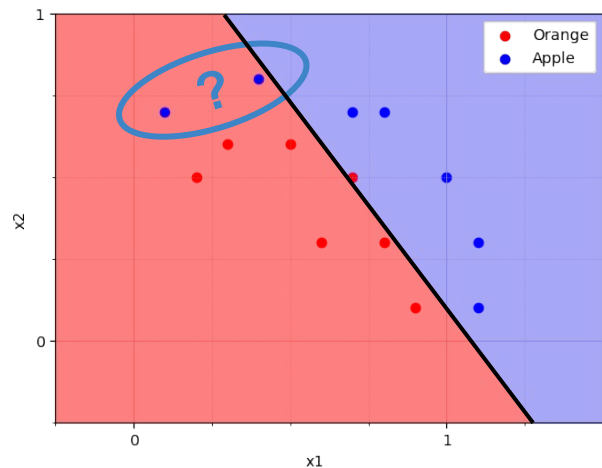
Labels



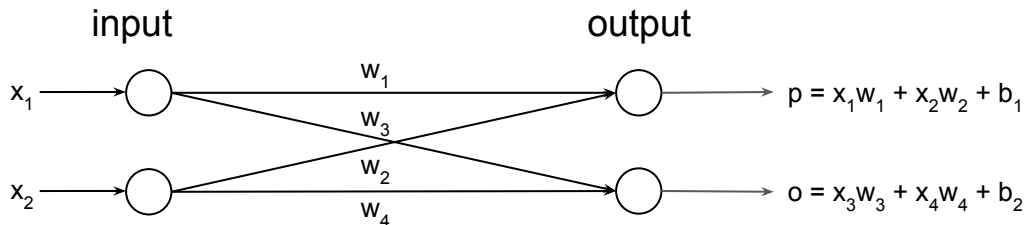
Data

x_1	x_2
0.2	0.5
0.3	0.6
0.5	0.6
0.6	0.3
0.7	0.5
0.8	0.3
0.9	0.1

x_1	x_2
0.1	0.7
0.4	0.8
0.7	0.7
0.8	0.7
1.0	0.5
1.1	0.1
1.1	0.3



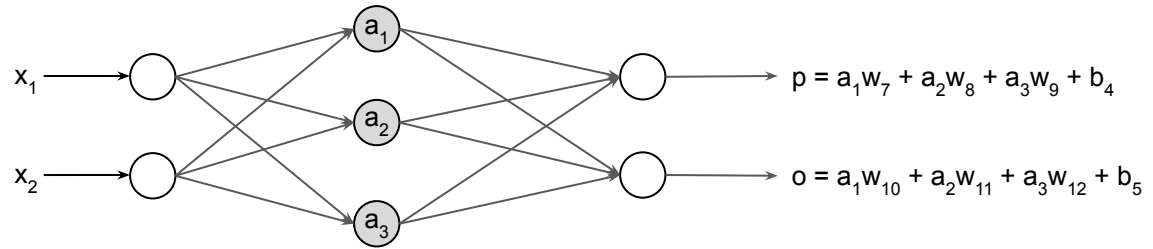
layers:



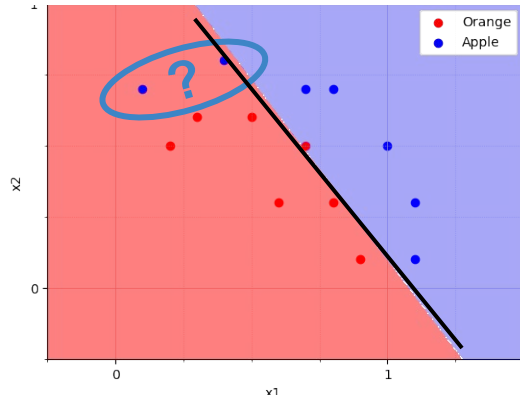
Multi-layer neural network

More complex but still linear

layers: input output



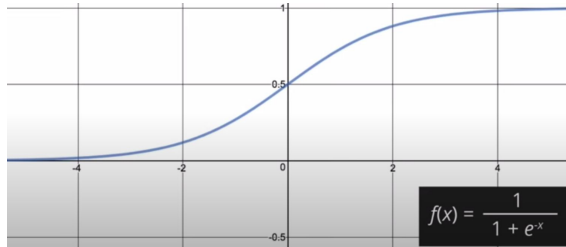
$$\begin{cases} a_1 = x_1w_1 + x_2w_2 + b_1 \\ a_2 = x_1w_3 + x_2w_4 + b_2 \\ a_3 = x_1w_5 + x_2w_6 + b_3 \end{cases}$$



Multi-layer neural network

Activation function: one step towards non-linearity

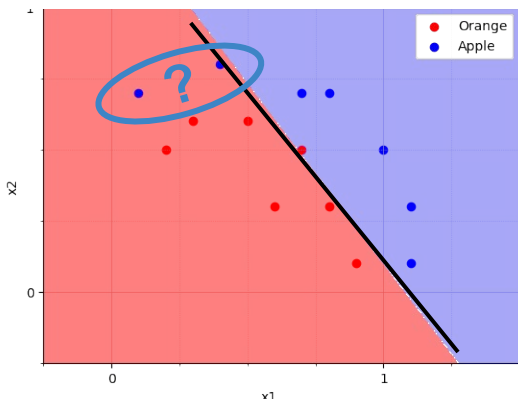
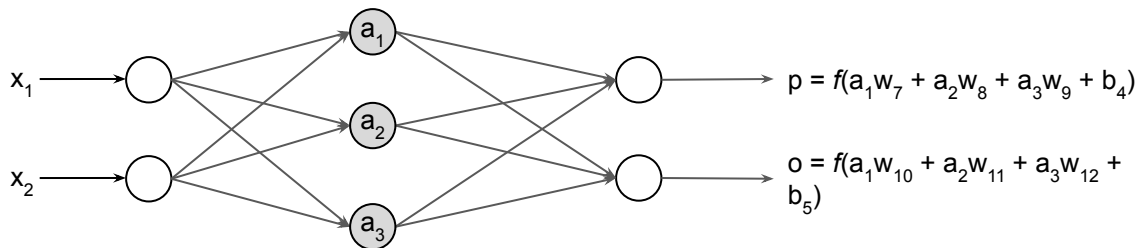
ex: sigmoid function



layers:

input

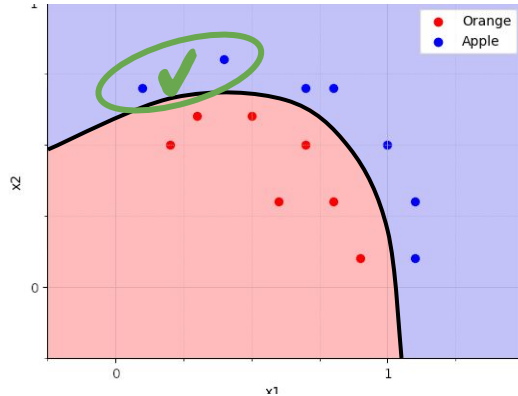
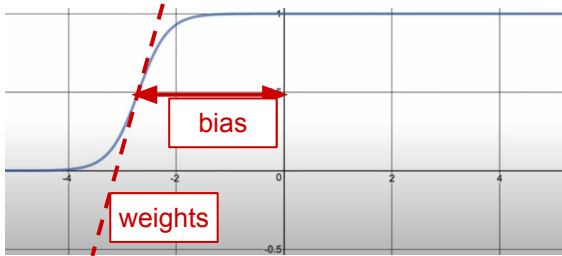
output



$$\begin{cases} a_1 = f(x_1w_1 + x_2w_2 + b_1) \\ a_2 = f(x_1w_3 + x_2w_4 + b_2) \\ a_3 = f(x_1w_5 + x_2w_6 + b_3) \end{cases}$$

Multi-layer neural network

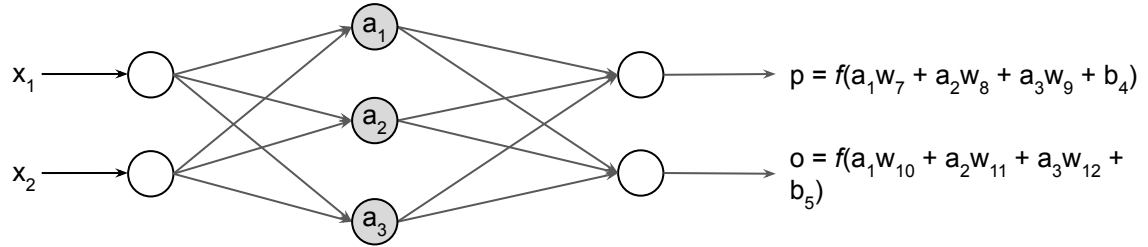
ex: sigmoid function



layers:

input

output



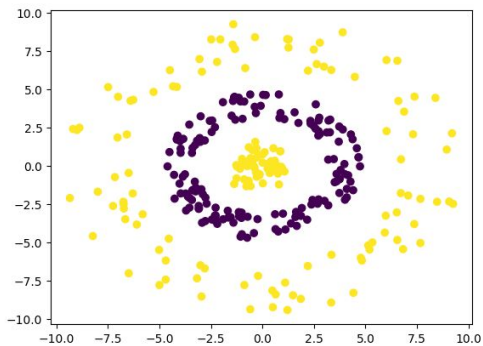
$$\begin{cases} a_1 = f(x_1w_1 + x_2w_2 + b_1) \\ a_2 = f(x_1w_3 + x_2w_4 + b_2) \\ a_3 = f(x_1w_5 + x_2w_6 + b_3) \end{cases}$$

How to set the parameters ?

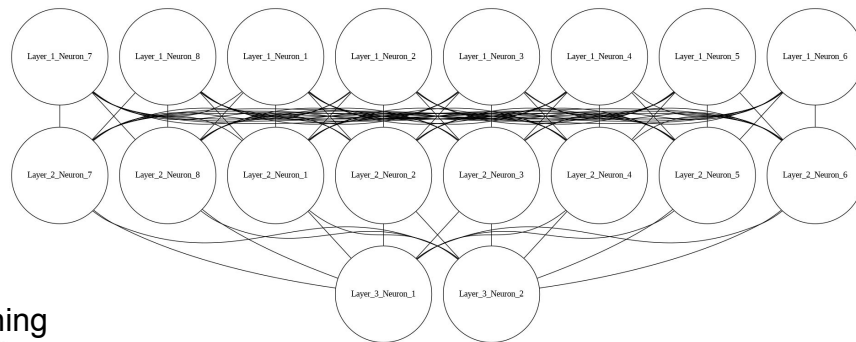
Multi-layer neural network

Automatic training

Données - labels

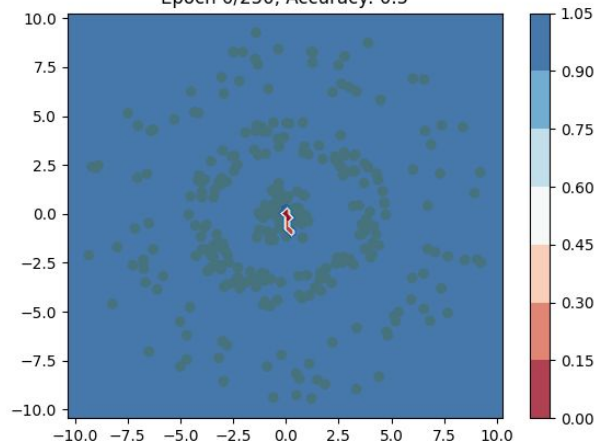


Network selection + activation
function



Training

Epoch 0/250, Accuracy: 0.5



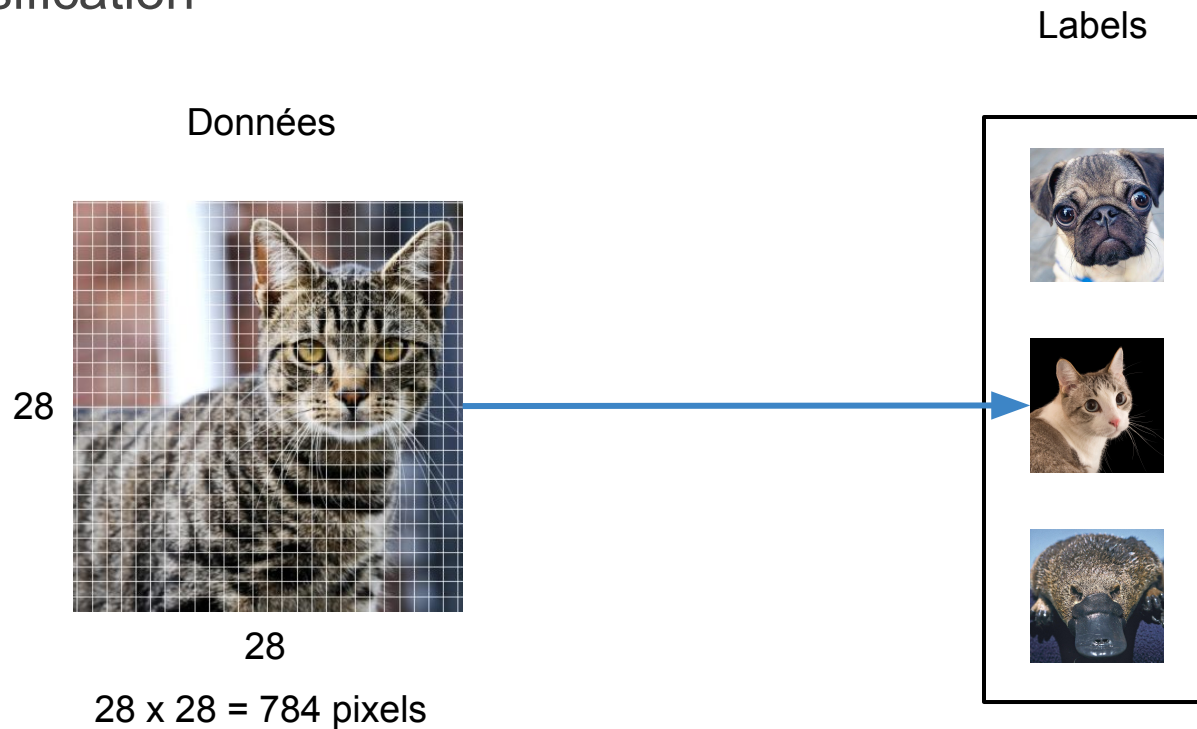
Iterative process:
updating neural network
weights

Accuracy = precision:
Ratio of well-ranked points

How does it
work?

Training the neural network

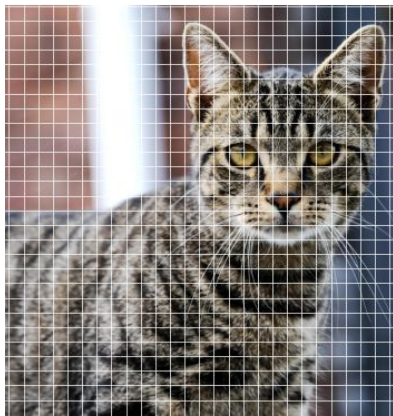
Image classification



Training the neural network

Forward propagation

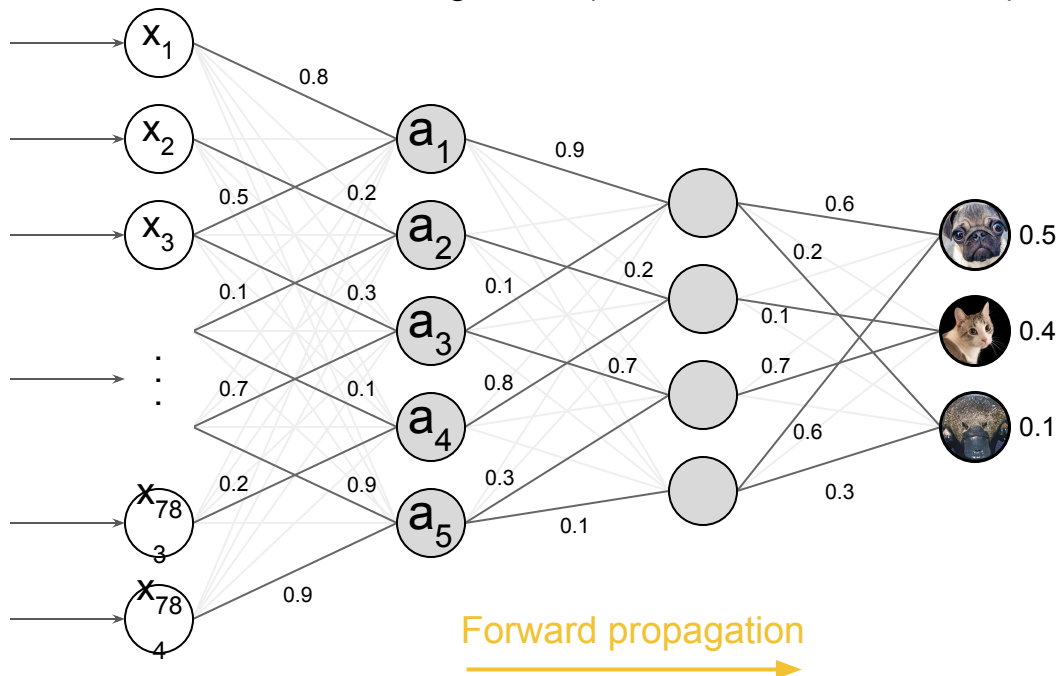
Data



28

28 x 28 = 784 pixels

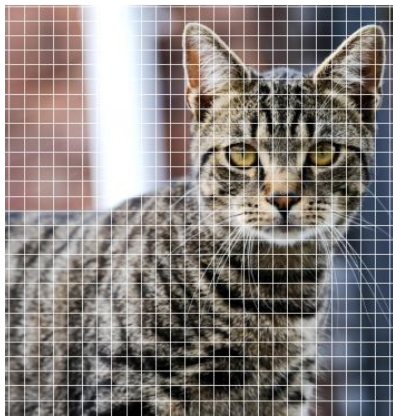
$$\text{e.g. } a_1 = f(0.8 x_1 + 0.5 x_3 + \dots + b_1)$$



Training the neural network

Backward propagation

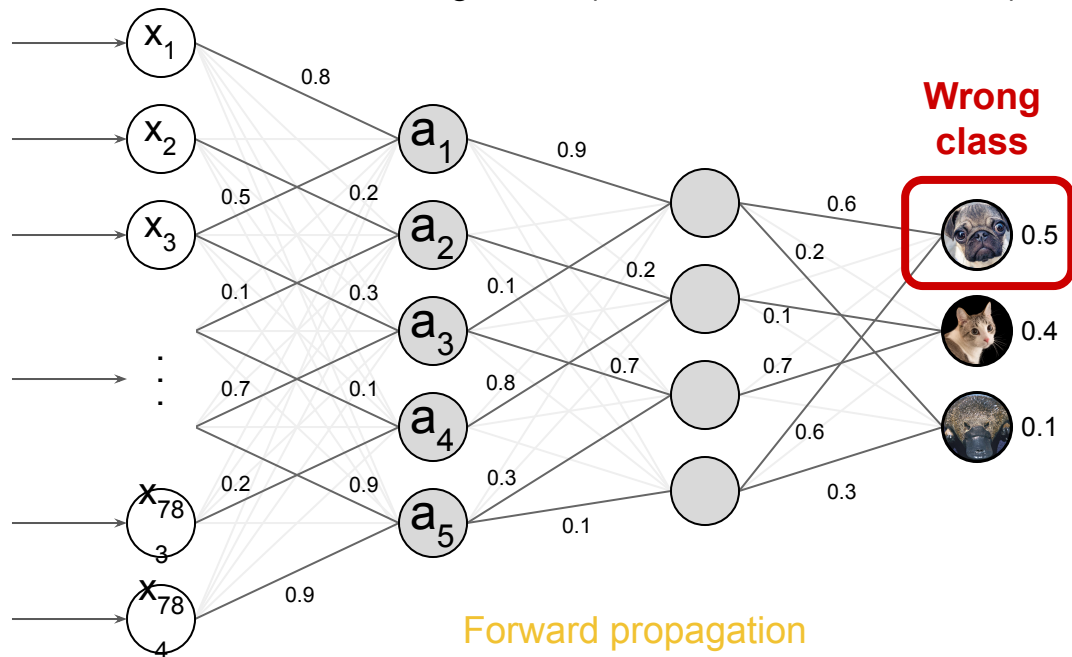
Data



28

28 x 28 = 784 pixels

$$\text{e.g. } a_1 = f(0.8 x_1 + 0.5 x_3 + \dots + b_1)$$

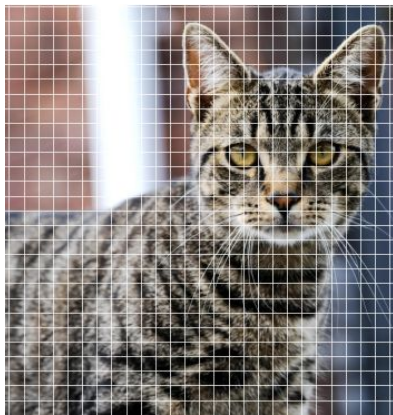


Truth	Error
0	-0.5
1	0.6
0	-0.1

Training the neural network

Convergence ?

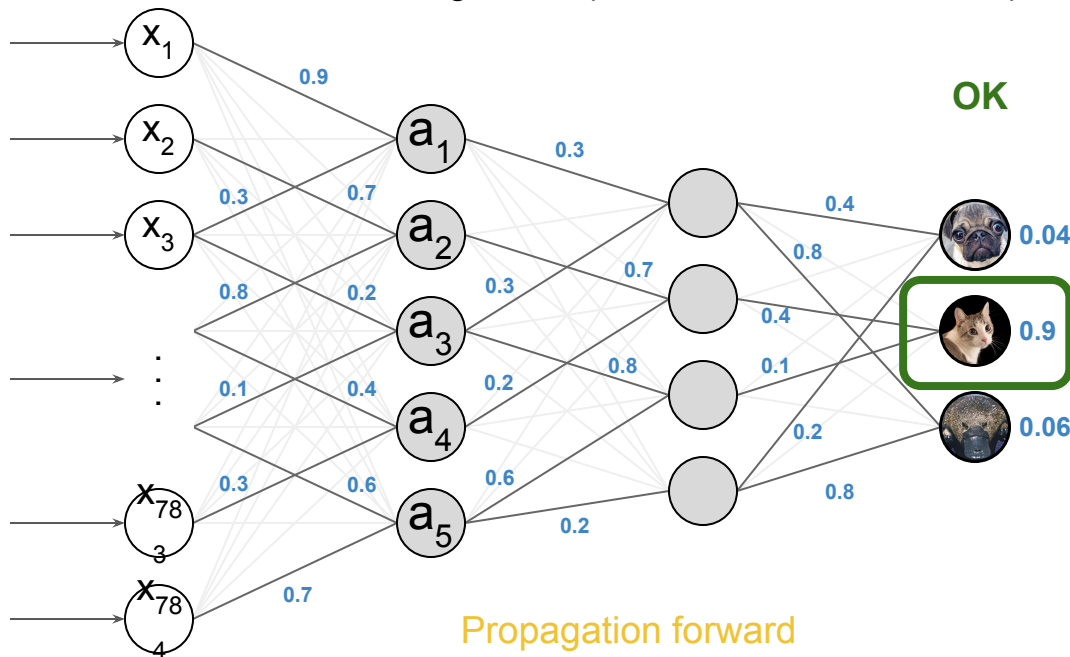
Data



28

28 x 28 = 784 pixels

$$\text{e.g. } a_1 = f(0.9 x_1 + 0.3 x_3 + \dots + b_1)$$



Truth	Error
0	-0.04
1	0.1
0	-0.06

Propagation forward
Backward propagation

Neural networks

Training

- We introduce the empirical loss over the entire dataset \mathcal{D} :

$$\text{EmpLoss}_{L, \mathcal{D}}(h_w) = \frac{1}{m} \sum_{(x,y) \in \mathcal{D}} L(y, h_w(x)).$$

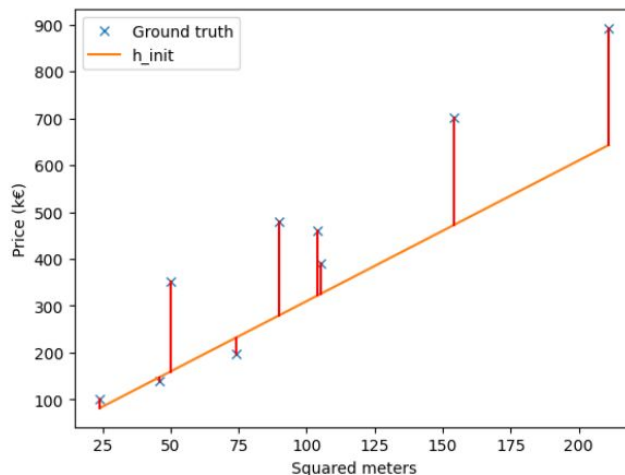
- For an example (x, y) and predictor h_w , we can use the loss functions :

- ▶ L_1 -loss : $L_1(y, \hat{y}) = |y - h_w(x)|$,
- ▶ L_2 -loss : $L_2(y, \hat{y}) = (y - h_w(x))^2$

To optimize the perceptron, we solve :

$$\hat{w}^* = \arg \min_w \text{Loss}(w).$$

⇒ using L2-loss :
 Perceptron is equivalent to linear regression !



Supervised learning Task

Algorithm Gradient descent algorithm

Dataset \mathcal{D} : inputs $X \rightarrow$ outputs y

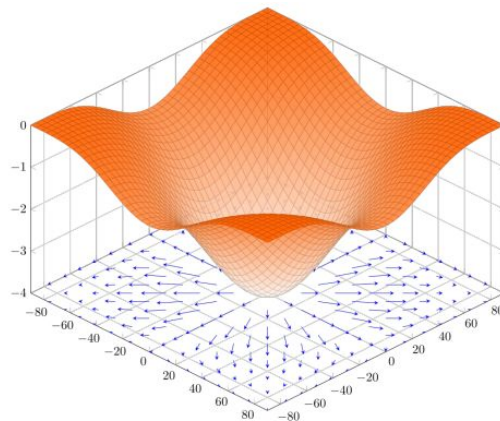
Initialize weights w_i

while not converged **do**

 Compute prediction $h_w(x)$ and loss
 $Loss(w)$

 Update weights with step size α :

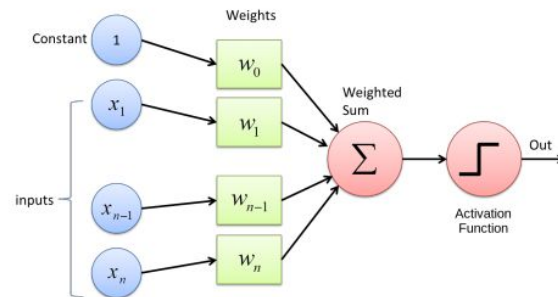
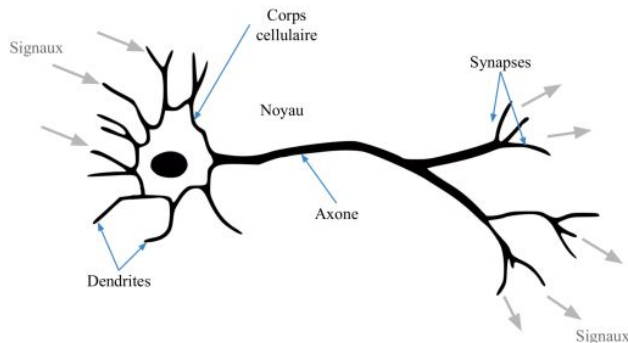
$$w \leftarrow w - \alpha \times \vec{\nabla} Loss(w)$$



$$\vec{\nabla} Loss(w) = \begin{bmatrix} \frac{\partial}{\partial w_0} Loss(w) \\ \frac{\partial}{\partial w_1} Loss(w) \\ \vdots \\ \frac{\partial}{\partial w_m} Loss(w) \end{bmatrix}$$

Neural networks

Perceptron



Given an **input** $x^T = [x_1 \ \cdots \ x_n]$, we define a **perceptron** with the (synaptic) **weights** $w^T = [w_1 \ \cdots \ w_n]$ and bias w_0 to compute the **output** $h_w(x)$ as

$$h_w(x) = g(w_0 + \sum_{i=1}^n w_i x_i) \quad (1)$$

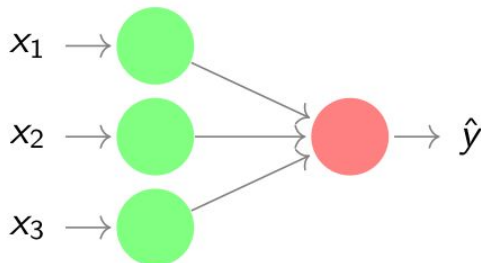
Hypothesis space : linear functions, Loss L2-loss (e.g.)

Training : gradient descent updates $w \leftarrow w - \alpha \times \vec{\nabla} \text{Loss}(w)$

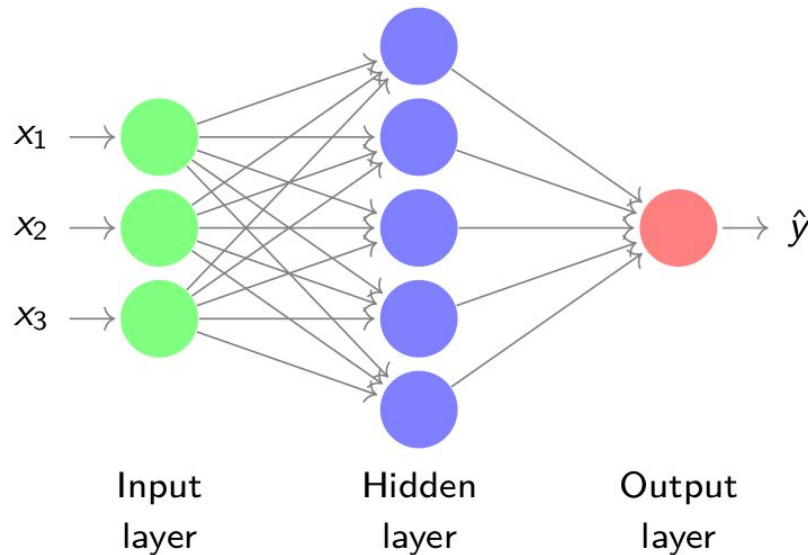
Neural networks

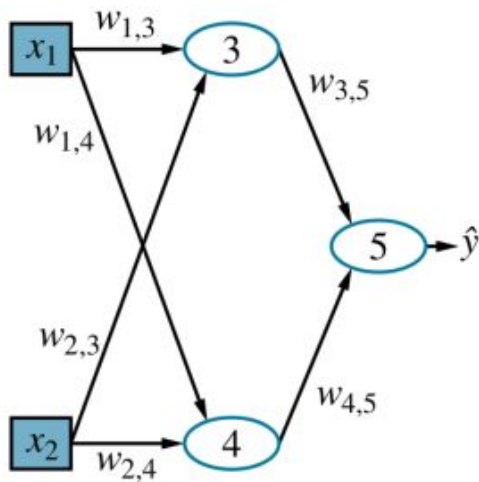
From 1 neuron to a brain

Perceptron



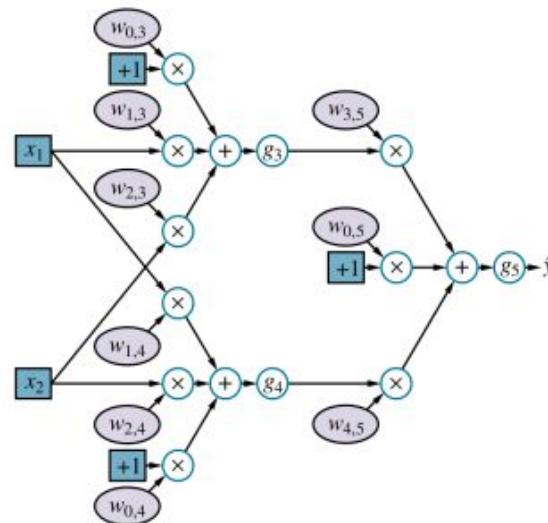
Multilayer perceptron





Neural networks

From 1 neuron to a brain: the chain rule



Neural networks

Full training

Network \leftarrow neural network with initial weights
while not converged **do**
 BACKPROP-ITER(*E*, *Network*)

Problem :

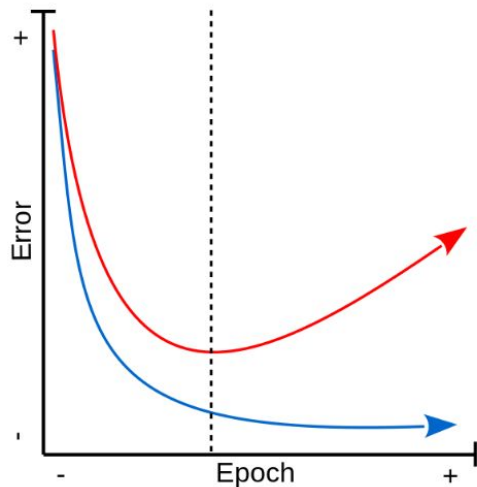
- ▶ slow, requires the derivatives
 - ▶ gradient computation is costly and increases with
 - ▶ number of weight
 - ▶ number of examples
- $\Rightarrow O(|w| \times |E|)$

Solution : (*Stochastic/mini-batch gradient descent*) :
select a small subset of example on which to propagate the error

Network \leftarrow neural network with initial weights
while not converged **do**
 MiniBatch \leftarrow sample(*E*, *k*)
 BACKPROP-ITER(*MiniBatch*, *Network*)

Neural networks

Convergence



Error on training set (blue) and
test set (red)

Problem :

- ▶ training tend to overfit the data
- ▶ we cannot touch the test data

Solution :

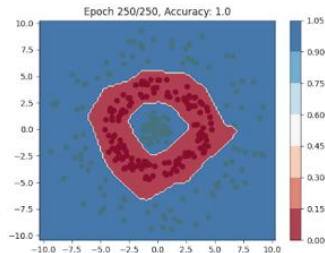
- ▶ stop when performance decreases on the validation set,
- ▶ do not use validation set for training !

Neural networks

In practice

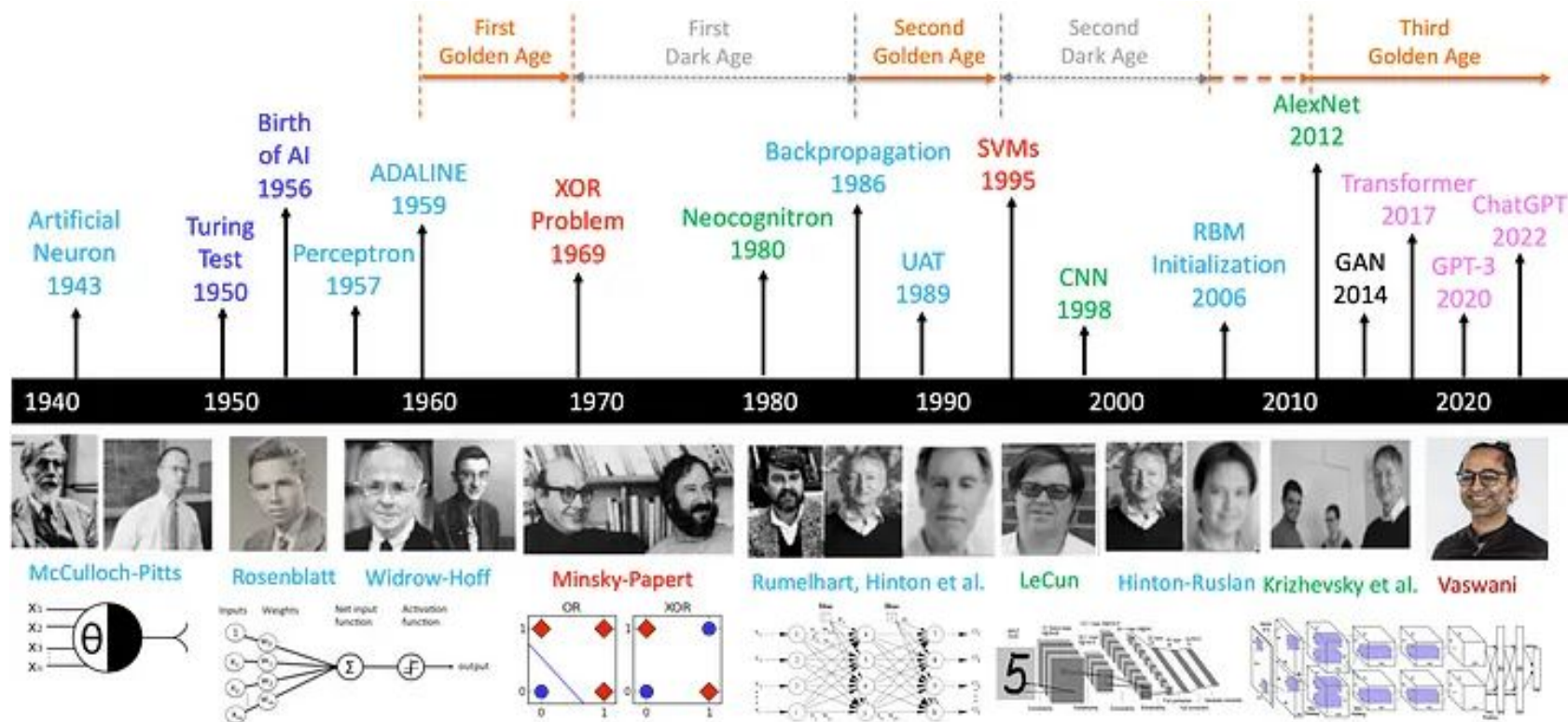
Use existing libraries ! Also contains all elements to develop new machine learning methods (used in research) :

- ▶ Scikit-learn 
- ▶ Keras  + Tensorflow 



```
# Création du modèle de réseau de neurones
model = tf.keras.Sequential([
    tf.keras.layers.Dense(8, activation='relu', input_shape=(2,)),
    tf.keras.layers.Dense(8, activation='relu'),
    tf.keras.layers.Dense(2, activation='softmax')
])
# Compilation du modèle
model.compile(optimizer='adam', loss='categorical_crossentropy', metrics=['accuracy'])
# Entraînement sur data avec labels
model.fit(data, labels, epochs=250, verbose=0)
# Prédiction sur data test
predicted_labels = model.predict(data_test)
```

A brief history of AI with deep learning



Convolutional Neural networks

Image analysis

Is there a left turn in the following images ?

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

Convolutional Neural networks

Convolution Kernel

$$\text{input} = \begin{bmatrix} x_1 & x_2 & x_3 \\ x_4 & x_5 & x_6 \\ x_7 & x_8 & x_9 \end{bmatrix}$$

$$\text{kernel} = \begin{bmatrix} w_1 & w_2 & w_3 \\ w_4 & w_5 & w_6 \\ w_7 & w_8 & w_9 \end{bmatrix}$$

$$f_w(x) = \sum_i w_i x_i$$

$$\text{kernel} = \begin{bmatrix} -1 & -1 & -1 \\ -1 & 1 & 1 \\ -1 & 1 & -1 \end{bmatrix}$$

$$f_w\left(\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 0 \end{bmatrix}\right) = 3 \quad f_w\left(\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}\right) = 2 \quad f_w\left(\begin{bmatrix} 0 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 0 \end{bmatrix}\right) = 1 \quad f_w\left(\begin{bmatrix} 0 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix}\right) = 2$$

- ▶ When $f_w(x) = 3$ our kernel is able to detect a “right turn” in a 3x3 image.⁴
- ▶ Our kernel is essentially a neural unit (perceptron).
- ▶ The weights could be learned

Convolutional Neural networks

Scaling up to 4

$$\begin{array}{c}
 \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 1 & 0 & 1 \end{bmatrix} \\
 \\
 TL = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 0 \end{bmatrix} \quad TR = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \\
 \\
 BL = \begin{bmatrix} 0 & 1 & 1 \\ 0 & 1 & 0 \\ 1 & 1 & 0 \end{bmatrix} \quad BR = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix}
 \end{array}$$

Key idea : apply the convolutional unit to each 3x3 sub-images.

$$\begin{bmatrix} f_w(TL) & f_w(TR) \\ f_w(BL) & f_w(BR) \end{bmatrix} = \begin{bmatrix} 3 & -3 \\ -1 & -4 \end{bmatrix} = \begin{bmatrix} a_{17} & a_{18} \\ a_{19} & a_{20} \end{bmatrix}$$

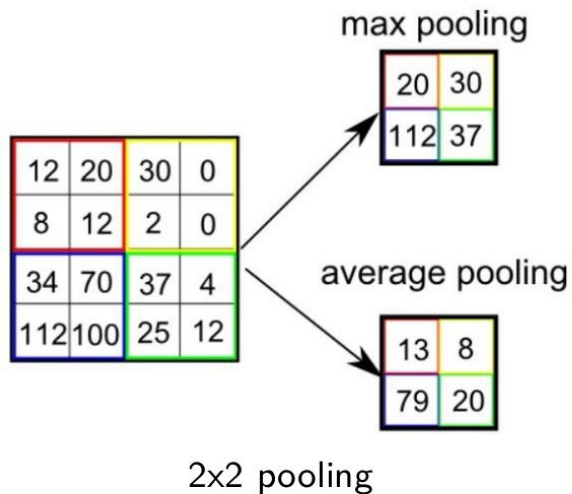
Interpretation : there is a “right turn” in the top left corner, the rest is garbage.

Key insight :

- ▶ in this convolutional layer, we have 4 (2x2) output nodes
- ▶ each uses the **same** function, with the **same weights**
- ▶ the kernel is trained to detect a feature independently of its location in the source image

Convolutional Neural networks

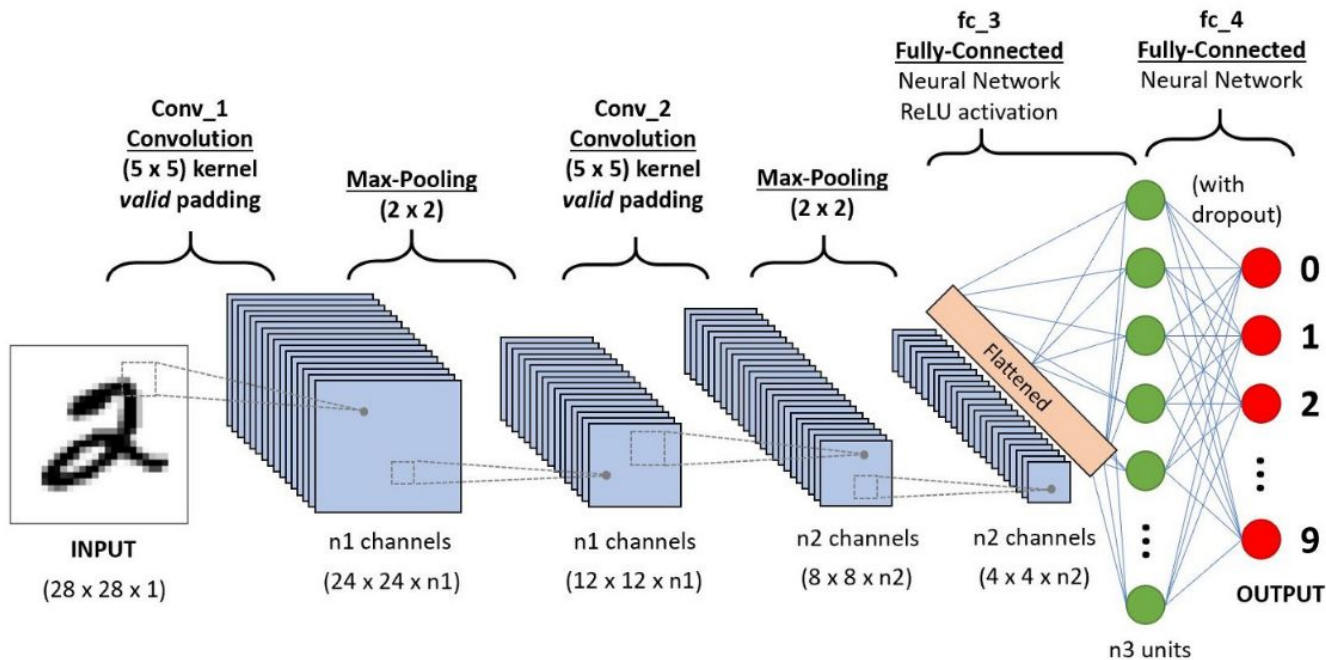
Combine with other types of kernels



- ▶ reduces dimensionality and variance
- ▶ suppresses the noise

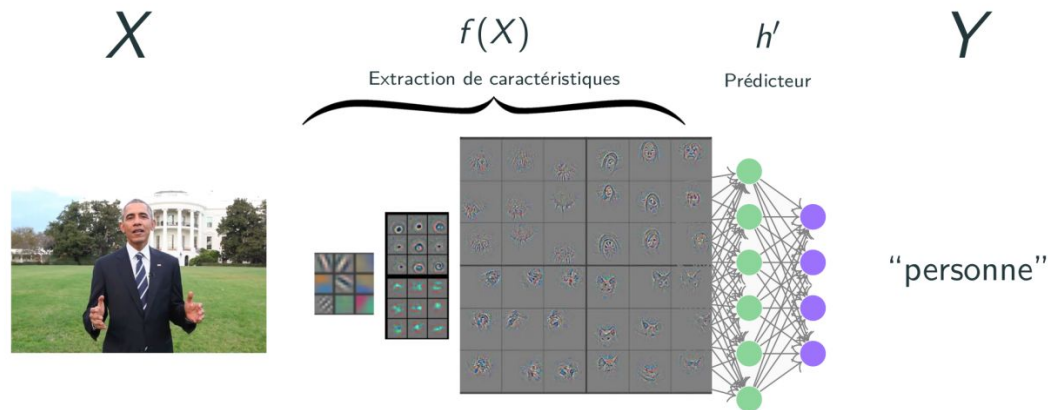
Convolutional Neural networks

Combine with other types of kernels



Convolutional Neural networks

Learns what to look at

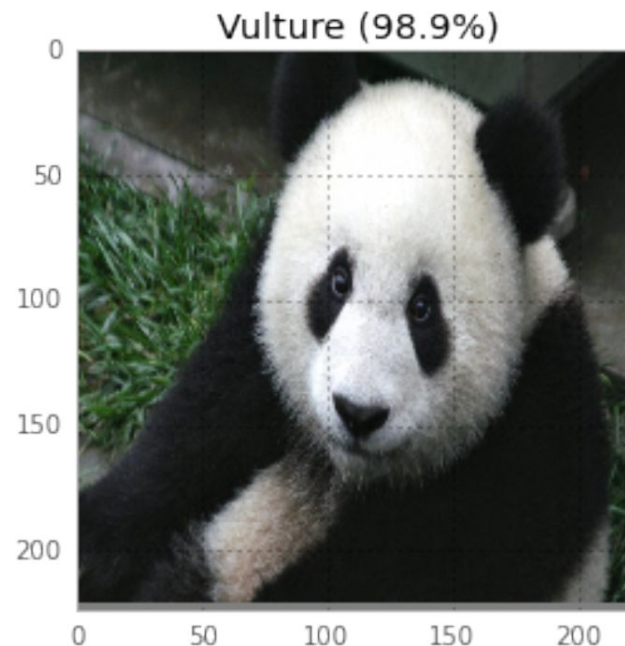
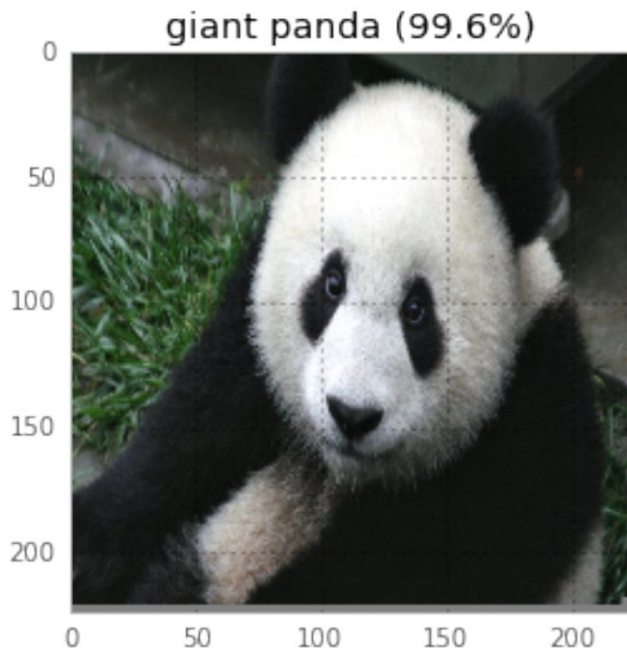


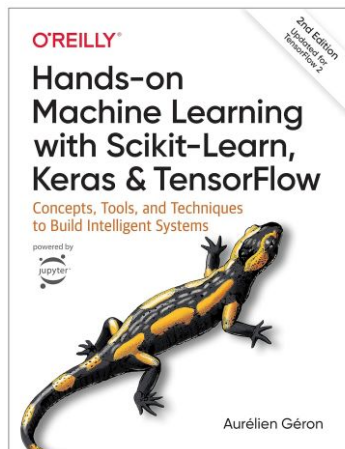
We can interpret CNN w.r.t. representation learning :

- ▶ the convolutional part is extractor of features/characteristics $f(X)$,
- ▶ the dense layers at the end play the role of our predictor h' .

Thus, deep learning allows to learn characteristics additionally to the predictor !

Some work left...
See you on wednesday





Got time a demo ?
Thank you for your attention

